### **Graduate Computer Architecture**

# Handout 2 – Instruction Level Parallelism, part A

## Outline

- ILP
- Compiler techniques to increase ILP
- Loop Unrolling
- Static Branch Prediction
- Dynamic Branch Prediction
- Overcoming Data Hazards with Dynamic Scheduling
- (Start) Tomasulo Algorithm
- Conclusion

## **Instruction Level Parallelism**

- Pipelining become universal technique in 1985
  - Overlaps execution of instructions
  - Exploits "Instruction Level Parallelism"
- Beyond this, there are two main approaches:
  - Hardware-based dynamic approaches
    - » Used in server and desktop processors
  - Compiler-based static approaches (VLIW)
    - » Not as successful outside of scientific applications

## **Recall from Pipelining Review**

- Pipeline CPI = Ideal pipeline CPI + Structural Stalls + Data Hazard Stalls + Control Stalls
  - <u>Ideal pipeline CPI</u>: measure of the maximum performance attainable by the implementation
  - <u>Structural hazards</u>: HW cannot support this combination of instructions
  - <u>Data hazards</u>: Instruction depends on result of prior instruction still in the pipeline
  - <u>Control hazards</u>: Caused by delay between the fetching of instructions and decisions about changes in control flow (branches and jumps)

### **Instruction Level Parallelism**

- Instruction-Level Parallelism (ILP): overlap the execution of instructions to improve performance
- 2 approaches to exploit ILP:
  - 1) Rely on hardware to help discover and exploit the parallelism dynamically (e.g., Pentium 4, AMD Opteron, IBM Power), and
  - 2) Rely on software technology to find parallelism, statically at compile-time (e.g., Itanium 2)
- On this topic spend our time will.

## Instruction-Level Parallelism (ILP)

- Basic Block (BB) ILP is quite small
  - BB: a straight-line code sequence with no branches in except to the entry and no branches out except at the exit
  - average dynamic branch frequency 15% to 25%
     => 4 to 7 instructions execute between a pair of branches
  - Plus instructions in BB likely to depend on each other
- To obtain substantial performance enhancements, we must exploit ILP across multiple basic blocks
- Simplest: <u>loop-level parallelism</u> to exploit parallelism among iterations of a loop. E.g.,

### **Loop-Level Parallelism**

- Exploit loop-level parallelism to parallelism by "unrolling loop" either by
- 1. dynamic via branch prediction or
- 2. static via loop unrolling by compiler (Another way is vectors)
- Determining instruction dependence is critical to Loop Level Parallelism
- If 2 instructions are
  - <u>parallel</u>, they can execute simultaneously in a pipeline of arbitrary depth without causing any stalls (assuming no structural hazards)
  - <u>dependent</u>, they are not parallel and must be executed in order, although they may often be partially overlapped

### **Data Dependence and Hazards**

 Instr<sub>J</sub> is data dependent (aka true dependence) on Instr<sub>I:</sub> (aka: also known as)

1. Instr<sub>J</sub> tries to read operand before Instr<sub>I</sub> writes it

 $\int I: add r1, r2, r3$ J: sub r4, r1, r3

- 2. or  $Instr_J$  is data dependent on  $Instr_K$  which is dependent on  $Instr_I$
- If two instructions are data dependent, they cannot execute simultaneously or be completely overlapped
- Data dependence in instruction sequence
   ⇒ data dependence in source code ⇒ effect of original data dependence must be preserved
- If data dependence caused a hazard in pipeline, called a Read After Write (RAW) hazard

## **ILP and Data Dependencies, Hazards**

- HW/SW must preserve program order: instructions would execute in order if executed sequentially as determined by original source program
  - Dependences are a property of programs
- Presence of dependence indicates potential for a hazard, but actual hazard and length of any stall is property of the pipeline
- Importance of the data dependencies
  - 1) indicates the possibility of a hazard
  - 2) determines order in which results must be calculated
  - 3) sets an upper bound on how much parallelism can possibly be exploited
- HW/SW goal: exploit parallelism by preserving program order only where it affects the outcome of the program

### Name Dependence #1: Anti-dependence

- Name dependence: when 2 instructions use same register or memory location, called a name, but no flow of data between the instructions associated with that name; 2 versions of name dependence
- Instr<sub>J</sub> writes operand <u>before</u> Instr<sub>I</sub> reads it

I: sub r4,r1,r3
J: add r1,r2,r3
K: mul r6,r1,r7

Called an "anti-dependence" by compiler writers. This results from reuse of the name "r1"

• If anti-dependence caused a hazard in the pipeline, called a Write After Read (WAR) hazard

### Name Dependence #2: Output dependence

• Instr<sub>J</sub> writes operand <u>before</u> Instr<sub>I</sub> writes it.

I: sub r1,r4,r3
J: add r1,r2,r3
K: mul r6,r1,r7

- Called an "output dependence" by compiler writers This also results from the reuse of name "r1"
- If output-dependence caused a hazard in the pipeline, called a Write After Write (WAW) hazard
- Instructions involved in a name dependence can execute simultaneously if name used in instructions is changed so instructions do not conflict
  - Register renaming resolves name dependence for regs
  - Either by compiler or by HW

## **Control Dependencies**

 Every instruction is control dependent on some set of branches, and, in general, these control dependencies must be preserved to preserve program order

```
if p1 {
    S1;
};
if p2 {
    S2;
```

• S1 is control dependent on p1, and S2 is control dependent on p2 but not on p1.

## **Control Dependence Ignored**

- Control dependence needs not be preserved
  - willing to execute instructions that should not have been executed, thereby violating the control dependences, if can do so without affecting correctness of the program
- Instead, 2 properties critical to program correctness are
  - 1) exception behavior and
  - 2) data flow

### **Exception Behavior**

- Example:

DADDU	R2,R3,R4
BEQZ	R2,L1
LW	R1,0(R2)

L1:

– (Assume branches not delayed)

• Problem with moving LW before BEQZ?

### **Data Flow**

- Data flow: actual flow of data values among instructions that produce results and those that consume them
  - branches make flow dynamic, determine which instruction is supplier of data
- Example:

DADDU	<u>R1</u> ,R2,R3
BEQZ	R4,L
DSUBU	<u>R1</u> ,R5,R6
L:	
OR	R7, <mark>R1</mark> ,R8

• OR depends on DADDU or DSUBU? Must preserve data flow on execution

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### **Software Techniques - Example**

- This code, add a scalar to a vector: for (i=1000; i>0; i=i-1)
   x[i] = x[i] + s;
- Assume following latencies for all examples

Ignore delayed branch in these examples

Instruction producing result	Instruction using result	Latency in cycles	stalls between in cycles
FP ALU op	Another FP ALU op	4	3
FP ALU op	Store double	3	2
Load double	FP ALU op	1	1
Load double	Store double	1	0
Integer op	Integer op	1	0

### **FP Loop: Where are the Hazards?**

- First translate into MIPS code:
  - -To simplify, assume 8 is lowest address
  - Loop: L.D F0,0(R1);F0=vector element ADD.D F4,F0,F2;add scalar from F2 S.D 0(R1),F4;store result DADDUI R1,R1,-8;decrement pointer 8B (DW) BNEZ R1,Loop ;branch R1!=zero

## **FP Loop Showing Stalls**

1	Loop:	L.D	<pre>F0,0(R1)</pre>	;F0=vector element
2		stall		
3		ADD.D	<b>F4,F0,F2</b>	;add scalar in F2
4		stall		
5		stall		
6		S.D	0(R1), <mark>F4</mark>	;store result
7		DADDUI	R1,R1,-8	;decrement pointer 8B (DW)
8		stall		;assumes can't forward to branch
9		BNEZ	R1,Loop	;branch R1!=zero

Instruction producing result	Instruction using result	Latency in clock cycles
FP ALU op	Another FP ALU op	3
FP ALU op	Store double	2
Load double	FP ALU op	1

• 9 clock cycles: Rewrite code to minimize stalls? 2017/10/11

## **Revised FP Loop Minimizing Stalls**

1 Loop:	L.D	<pre>F0,0(R1)</pre>					
2	DADDUI	R1,R1,-8					
3	ADD.D	F4,F0,F2					
4	stall						
5	stall						
6	S.D	<mark>8(R1),F4</mark>	;altered	offset	when	move	DSUBUI
7	BNEZ	R1,Loop					

#### Swap DADDUI and S.D by changing address of S.D

Instruction producing result	Instruction using result	Latency in clock cycles
FP ALU op	Another FP ALU op	3
FP ALU op	Store double	2
Load double	FP ALU op	1

7 clock cycles, but just 3 for execution (L.D, ADD.D,S.D), 4 for loop overhead; How make faster? 2017/10/11 20

### Unroll Loop Four Times (straightforward way)

1			_1 cyc	le stall		
T TOOD:	L.D	F0,0(R1)				Rewrite loop to
3	ADD.D	F4,F0,F2	2 cyc	cles stall		minimize stalls?
6	S.D	0(R1), F4	;drop	DSUBUI	&	BNEZ
7	L.D	F6,-8(R1)				
9	ADD.D	F8,F6,F2				
12	S.D	-8(R1),F8	;drop	DSUBUI	&	BNEZ
13	L.D	F10,-16(R1)				
15	ADD.D	F12,F10,F2				
18	S.D	-16(R1),F12	;drop	DSUBUI	&	BNEZ
19	L.D	F14,-24(R1)				
21	ADD.D	F16,F14,F2				
24	S.D	-24(R1),F16				
25	DADDUI	R1,R1, <b>#-32</b>	;alter	r to 4*8	3	
26	BNEZ	R1,LOOP				

#### 27 clock cycles, or 6.75 per iteration (Assumes R1 is multiple of 4)

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## **Unrolled Loop Detail**

- Do not usually know upper bound of loop
- Suppose it is n, and we would like to unroll the loop to make k copies of the body
- Instead of a single unrolled loop, we generate a pair of consecutive loops:
  - 1st executes (n mod k) times and has a body that is the original loop
  - 2nd is the unrolled body surrounded by an outer loop that iterates (n/k) times
- For large values of n, most of the execution time will be spent in the unrolled loop

### **Unrolled Loop That Minimizes Stalls**

1 Loop:	L.D	F0,0(R1)
2	L.D	F6,-8(R1)
3	L.D	F10,-16(R1)
4	L.D	F14,-24(R1)
5	ADD.D	F4,F0,F2
6	ADD.D	F8,F6,F2
7	ADD.D	F12,F10,F2
8	ADD.D	F16,F14,F2
9	S.D	0(R1),F4
10	S.D	-8(R1),F8
11	S.D	-16(R1),F12
12	DSUBUI	R1,R1,#32
13	S.D	8(R1),F16 ; 8-32 = -24
14	BNEZ	R1,LOOP

14 clock cycles, or 3.5 per iteration

# **5 Loop Unrolling Decisions**

- Requires understanding how one instruction depends on another and how the instructions can be changed or reordered given the dependences:
- 1. Determine loop unrolling useful by finding that loop iterations were independent (except for maintenance code)
- 2. Use different registers to avoid unnecessary constraints forced by using same registers for different computations
- 3. Eliminate the extra test and branch instructions and adjust the loop termination and iteration code
- 4. Determine that loads and stores in unrolled loop can be interchanged by observing that loads and stores from different iterations are independent
  - Transformation requires analyzing memory addresses and finding that they do not refer to the same address
- 5. Schedule the code, preserving any dependences needed to yield the same result as the original code

# **3 Limits to Loop Unrolling**

- 1. Decrease in amount of overhead amortized with each extra unrolling
  - Amdahl's Law
- 2. Growth in code size
  - For larger loops, concern it increases the instruction cache miss rate
- 3. <u>Register pressure</u>: potential shortfall in registers created by aggressive unrolling and scheduling
  - If not be possible to allocate all live values to registers, may lose some or all of its advantage
- Loop unrolling reduces impact of branches on pipeline; another way is branch prediction

## **Static Branch Prediction**

- Previous lecture showed scheduling code around delayed branch
- To reorder code around branches, need to predict branch statically when compile
- Simplest scheme is to predict a branch as taken
  - Average misprediction = untaken branch frequency = 34% SPEC



## **Dynamic Branch Prediction**

- Why does prediction work?
  - Underlying algorithm has regularities
  - Data that are being operated on have regularities
  - Instruction sequence has redundancies that are artifacts of way that humans/compilers think about problems
- Is dynamic branch prediction better than static branch prediction?
  - Seems to be
  - There are a small number of important branches in programs which have dynamic behavior

## **Dynamic Branch Prediction**

- Performance = f(accuracy, cost of misprediction)
- Branch History Table: Lower bits of PC address index table of 1-bit values
  - Says whether or not branch taken last time
  - No address check
- Problem: in a loop, 1-bit BHT will cause two mispredictions):

For branch xx

- TTTTTTTTTTTTT (true behavior of branch xx)
- 1111111 (misprediction for NT))
  - 0 (change to 0 for misprediction, and misprediction for T now)
    - 1 (change to 1 for misprediction of **T**)

## **Dynamic Branch Prediction**

 Solution: 2-bit scheme where change prediction only if gets misprediction *twice*



- Green: go, taken
- Adds *hysteresis* to decision making process 2017/10/11

## **BHT Accuracy**

- Mispredict because either:
  - Wrong guess for that branch
  - Got branch history of wrong branch when indexing the table
- 4096 entry table:



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### **Correlated Branch Prediction**

- Idea: record *m* most recently executed branches as taken or not taken, and use that pattern to select the proper *n*-bit branch history table
- In general, (m,n) predictor means record last m branches to select between 2<sup>m</sup> history tables, each with n-bit counters

- Thus, old 2-bit BHT is a (0,2) predictor

• Global Branch History: *m*-bit shift register keeping T/NT status of last *m* branches.

## **Correlating Branches**

(2,2) predictor

Behavior of recent
 branches selects
 between four
 predictions of next
 branch, updating just
 that prediction



### **Accuracy of Different Schemes**



### **Tournament Predictors**

- Multilevel branch predictor
- Use *n*-bit saturating counter to choose between predictors
- Usual choice between global and local predictors



### **Tournament Predictors**

Tournament predictor using, say, 4K 2-bit counters indexed by local branch address. Chooses between:



## **Comparing Predictors**

- Advantage of tournament predictor is ability to select the right predictor for a particular branch
  - Particularly crucial for integer benchmarks.
  - A typical tournament predictor will select the global predictor almost 40% of the time for the SPEC integer benchmarks and less than 15% of the time for the SPEC FP benchmarks


#### Pentium 4 Misprediction Rate (per 1000 instructions, not per branch)



#### **Branch Target Buffers (BTB)**

- Branch target calculation is costly and stalls the instruction fetch.
- BTB stores PCs the same way as caches
- The PC of a branch is sent to the BTB
- When a match is found the corresponding Predicted PC is returned
- If the branch was predicted taken, instruction fetch continues at the returned predicted PC



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## **Dynamic Branch Prediction Summary**

- Prediction becoming important part of execution
- Branch History Table: 2 bits for loop accuracy
- Correlation: Recently executed branches correlated with next branch
  - Either different branches (GA)
  - Or different executions of same branches (PA), Per-Address
- Tournament predictors take insight to next level, by using multiple predictors
  - usually one based on global information and one based on local information, and combining them with a selector
  - In 2006, tournament predictors using  $\approx$  30K bits are in processors like the Power5 and Pentium 4
- Branch Target Buffer: include branch address & prediction

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## **Advantages of Dynamic Scheduling**

- Dynamic scheduling hardware rearranges the instruction execution to reduce stalls while maintaining data flow and exception behavior
- It handles cases when dependences unknown at compile time
  - it allows the processor to tolerate unpredictable delays such as cache misses, by executing other code while waiting for the miss to resolve
- It allows code that compiled for one pipeline to run efficiently on a different pipeline
- It simplifies the compiler
- Hardware speculation, a technique with significant performance advantages, builds on dynamic scheduling (next lecture)

#### **HW Schemes: Instruction Parallelism**

- Key idea: Allow instructions behind stall to proceed
  - DIVD F0,F2,F4 ADDD F10,F0,F8 SUBD F12,F8,F14
- Enables out-of-order execution and allows out-oforder completion (e.g., SUBD)
  - In a dynamically scheduled pipeline, all instructions still pass through issue stage in order (in-order issue)
- Will distinguish when an instruction begins execution and when it completes execution; between 2 times, the instruction is in execution
- Note: Dynamic execution creates WAR and WAW hazards and makes exceptions harder

## **Dynamic Scheduling Step 1**

- Simple pipeline had 1 stage to check both structural and data hazards: Instruction Decode (ID), also called Instruction Issue
- Split the ID pipe stage of simple 5-stage pipeline into 2 stages:
- Issue—Decode instructions, check for structural hazards
- Read operands—Wait until no data hazards, then read operands

## A Dynamic Algorithm: Tomasulo's

- For IBM 360/91 (before caches!)
  - $\Rightarrow$  Long memory latency
- Goal: High Performance without special compilers
- Small number of floating point registers (4 in 360) prevented interesting compiler scheduling of operations
  - This led Tomasulo to try to figure out how to get more effective registers
    renaming in hardware!
- Why Study 1966 Computer?
- The descendants of this have flourished!
  - Alpha 21264, Pentium 4, AMD Opteron, Power 5, ...

## **Tomasulo Algorithm**

- Control & buffers <u>distributed</u> with Function Units (FU)
  FU buffers called "reservation stations"; have pending operands
- Registers in instructions replaced by values or pointers to reservation stations(RS); called <u>register renaming</u>;
  - Renaming avoids WAR, WAW hazards
  - More reservation stations than registers, so can do optimizations compilers can't
- Results to FU from RS, <u>not through registers</u>, over <u>Common Data Bus</u> that broadcasts results to all FUs
  - Avoids RAW hazards by executing an instruction only when its operands are available
- Load and Stores treated as FUs with RSs as well
- Integer instructions can go past branches (predict taken), allowing FP ops beyond basic block in FP queue

#### **Tomasulo Organization**



Common Data Bus (CDB)

#### **Reservation Station Components**

#### **Op:** Operation to perform in the unit (e.g., + or –)

#### Vj, Vk: Value of Source operands

- Store buffers has V field, result to be stored

# **Qj**, **Qk**: Reservation stations producing source registers (value to be written)

- Note: Qj,Qk=0 => ready
- Store buffers only have Qj for RS producing result
- **Busy:** Indicates reservation station or FU is busy

**Register result status**—Indicates which functional unit will write each register, if one exists. Blank when no pending instructions that will write that register.

## **Three Stages of Tomasulo Algorithm**

#### **1. Issue**—get instruction from FP Op Queue

If reservation station free (no structural hazard), control issues instr & sends operands (renames registers).

#### 2. Execute—operate on operands (EX)

When both operands ready then execute; if not ready, watch Common Data Bus for result

#### 3. Write result—finish execution (WB)

Write on Common Data Bus to all awaiting units; mark reservation station available

#### • Normal data bus: data + destination ("go to" bus)

- <u>Common data bus</u>: data + <u>source</u> ("<u>come from</u>" bus)
  - 64 bits of data + 4 bits of Functional Unit <u>source</u> address
  - Write if matches expected Functional Unit (produces result)
  - Does the broadcast
- Example speed: 3 clocks for Fl .pt. +,-; 11 for \*; 41 clks for /

#### Instruction Tomasulo Example







#### Note: Can have multiple loads outstanding



- Note: registers names are removed ("renamed") in Reservation Stations; MULT issued
- Load1 completing; what is waiting for Load1? 2017/10/11



Load2 completing; what is waiting for Load2?



• Timer starts down for Add1, Mult1



#### Issue ADDD here despite name dependency on F6?



#### Add1 (SUBD) completing; what is waiting for it?



Instructio		Exec	Write									
Instruction j		k	Issue	Comp	Result			Busy	Address			
LD	F6	34+	R2	1	3	4		Load1	No			
LD	F2	45+	<b>R3</b>	2	4	5		Load2	No			
MULTD	FO	F2	<b>F</b> 4	3				Load3	No			
SUBD	F8	<b>F6</b>	F2	4	7	8						
DIVD	F10	F0	<b>F6</b>	5								
ADDD	F6	F8	F2	6								
Reservatio		<i>S1</i>	<i>S2</i>	RS	RS							
	Time	Name	Busy	Ор	Vj	Vk	Qj	Qk				
		Add1	No						Ī			
	1	Add2	Yes	ADDD	(M-M)	M(A2)						
		Add3	No									
	6	Mult1	Yes	MULTE	<b>M</b> (A2)	<b>R</b> (F4)						
		Mult2	Yes	DIVD		M(A1)	Mult1					
Register r	esult	statu	s:									
Clock				FO	F2	F4	<i>F6</i>	F8	<i>F10</i>	<i>F12</i>	•••	F30
9			FU	Mult1	M(A2)		Add2	(M-M)	Mult2			



## Add2 (ADDD) completing; what is waiting for it? 2017/10/11



- Write result of ADDD here?
- All quick instructions complete in this cycle! 2017/10/11









## Mult1 (MULTD) completing; what is waiting for it? 2017/10/11



#### Just waiting for Mult2 (DIVD) to complete 2017/10/11

# Faster than light computation (skip a couple of cycles)

Instructio		Exec	Write									
Instruction j		k	Issue	Comp	Result	-		Busy	Address			
LD	F6	34+	R2	1	3	4		Load1	No			
LD	F2	45+	<b>R</b> 3	2	4	5		Load2	No			
MULTD	FO	F2	<b>F</b> 4	3	15	16		Load3	No			
SUBD	<b>F8</b>	<b>F6</b>	F2	4	7	8						
DIVD	F10	FO	<b>F6</b>	5								
ADDD	F6	F8	F2	6	10	11						
Reservatio		<i>S1</i>	<i>S2</i>	RS	RS							
	Time	Name	Busy	Ор	Vj	Vk	Qj	Qk				
		Add1	No						]			
		Add2	No									
		Add3	No									
		Mult1	No									
	1	Mult2	Yes	DIVD	M*F4	M(A1)						
Register r	esult	statu	s:									
Clock				FO	F2	F4	F6	F8	<i>F10</i>	<i>F12</i>	•••	F30
55			FU	M*F4	M(A2)	(	M-M+N	(M-M)	Mult2			



#### • Mult2 (DIVD) is completing; what is waiting for it?



# • Once again: In-order issue, out-of-order execution and out-of-order completion.

# Why can Tomasulo overlap iterations of loops?

#### Register renaming

 Multiple iterations use different physical destinations for registers (dynamic loop unrolling).

#### Reservation stations

- Permit instruction issue to advance past integer control flow operations
- Also buffer old values of registers totally avoiding the WAR stall
- Other perspective: Tomasulo building data flow dependency graph on the fly

#### Tomasulo's scheme offers 2 major advantages

- 1. Distribution of the hazard detection logic
  - distributed reservation stations and the CDB
  - If multiple instructions waiting on single result, & each instruction has other operand, then instructions can be released simultaneously by broadcast on CDB
  - If a centralized register file were used, the units would have to read their results from the registers when register buses are available
- 2. Elimination of stalls for WAW and WAR hazards
## **Tomasulo Drawbacks**

- Complexity
  - delays of 360/91, MIPS 10000, Alpha 21264!
- Many associative stores (CDB) at high speed
- Performance limited by Common Data Bus
  - Each CDB must go to multiple functional units
    ⇒high capacitance, high wiring density
  - Number of functional units that can complete per cycle limited to one!
    - » Multiple CDBs  $\Rightarrow$  more FU logic for parallel assoc stores
- Non-precise interrupts!
  - We will address this later

## And In Conclusion ... #1

- Leverage Implicit Parallelism for Performance: Instruction Level Parallelism
- Loop unrolling by compiler to increase ILP
- Branch prediction to increase ILP
- Dynamic HW exploiting ILP
  - Works when can't know dependence at compile time
  - Can hide L1 cache misses
  - Code for one machine runs well on another

## And In Conclusion ... #2

- Reservations stations: *renaming* to larger set of registers + buffering source operands
  - Prevents registers as bottleneck
  - Avoids WAR, WAW hazards
  - Allows loop unrolling in HW
- Not limited to basic blocks (integer units gets ahead, beyond branches)
- Helps cache misses as well
- Lasting Contributions
  - Dynamic scheduling
  - Register renaming
  - Load/store disambiguation
- 360/91 descendants are Intel Pentium 4, IBM Power 5, AMD Athlon/Opteron, ...